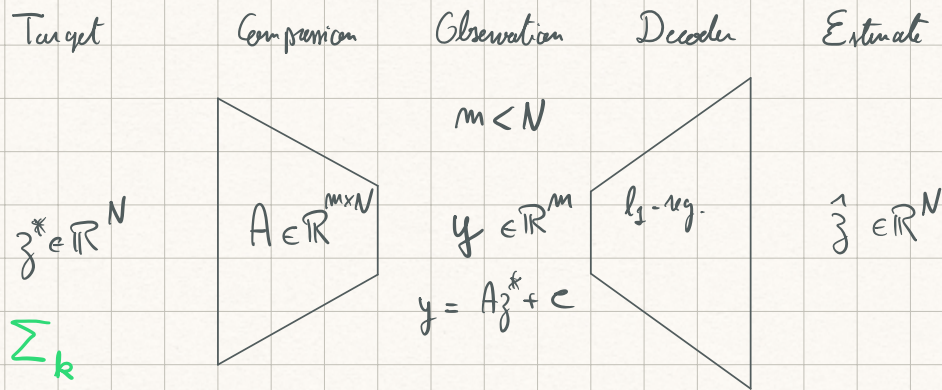


Lesson 4

The big picture:



⊗ Conditions on A

- ERC_k: $\forall S \subseteq [N], \#S = k, \quad \|(A_S^+) A_{S^c}\|_{1 \rightarrow 1} < 1$

where $A_S^+ = (A_S^T A_S)^{-1} A_S^T$ and A normalized ($\|A_i\|_2 = 1$)

$$\Leftrightarrow \left| \begin{array}{l} \|A_S^T A_S u\|_\infty > \|A_{S^c}^T A_S u\|_\infty \quad \forall u \neq 0. \\ A_S \text{ injective.} \end{array} \right.$$

- NSP₁: relative to a set $S \subseteq [N]$: $\forall v \in \mathbb{R}^N$ s.t. $v \in \text{ker}(A|_S)$

$$\|v_S\|_1 < \|v_{S^c}\|_1$$

- RIP_k: $\exists \delta_k > 0$ s.t. $\forall x \in \Sigma_k$

$$(1 - \delta_k) \|x\|_2^2 \leq \|Ax\|_2^2 \leq (1 + \delta_k) \|x\|_2^2$$

\rightarrow A normalized. $\|A_i\|_2^2 = 1$

• Coherence Property

Def: A with normalized columns

$$\mu = \mu(A) = \max_{1 \leq i \neq j \leq N} |\langle A_i, A_j \rangle|$$

Rk: A normalized

$$A^T A - I_d_N = \left(\delta_{i \neq j} \langle A_i, A_j \rangle \right)_{i,j}$$

Def: l_2 -coherence function

$$\mu_2(k) = \max_{i \in [N]} \max \left\{ \sum_{j \in S} |\langle A_i, A_j \rangle|, \right.$$

$$k \in [N-1]$$

$$\left. \begin{array}{l} S \subset [N], \\ \#S = k, i \notin S \end{array} \right\}$$

Note that, $\forall k \in [N-1]$,

$$\mu \leq \mu_{\frac{1}{2}}(k) \leq k\mu$$

Theorem (Coherence - RIP)

- A normalized
- $\forall x \in \Sigma_{\substack{k \\ 2k}}$,

$$(1 - \mu_{\frac{1}{2}}(k-1)) \|x\|_2^2 \leq \|Ax\|_2^2 \leq \dots \\ \dots (1 + \mu_{\frac{1}{2}}(k-1)) \|x\|_2^2$$

If $\mu_{\frac{1}{2}}(k-1) < 1$ Then RIP _{$\substack{k \\ 2k}$} holds

Proof: • Let $S \subset [N]$ be s.t. $\#S = k$

• Let $x \in \Sigma_k$ be s.t. $\text{Supp } x = S$

$$\|Ax\|_2^2 = x_S^T A_S^T A_S x_S$$

(indeed $Ax = A_S x_S$)

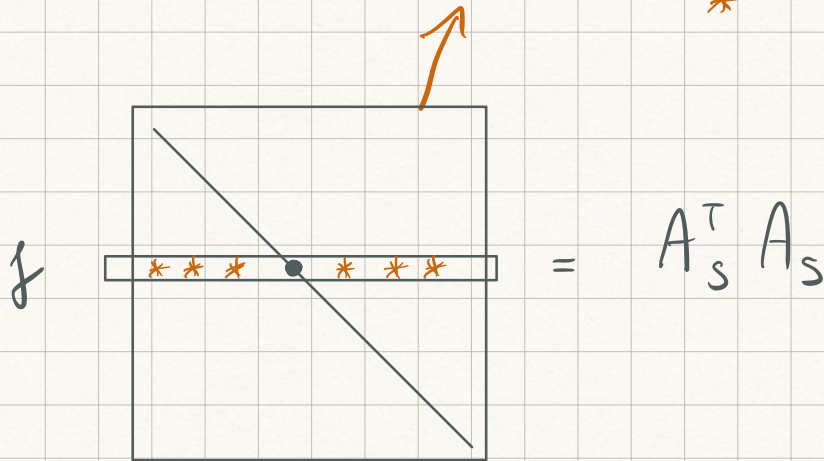
$$\lambda_{\max} = \max_{\substack{x \in \mathbb{R}^N \\ \text{Supp } x \subset S \\ \|x\|_2 = 1}} \left\{ \langle A_S^T A_S x_S, x_S \rangle \right\}$$

$$\lambda_{\min} = \min_{\substack{x \in \mathbb{R}^N \\ \text{Supp } x \subset S \\ \|x\|_2 = 1}} \left\{ \langle A_S^T A_S x_S, x_S \rangle \right\}$$

Note that:

$$\cdot (A_S^T A_S)_{ii} = 1$$

$$\cdot \lambda_j = \sum_{l \in S, l \neq j} \underbrace{|(A_s^T A_s)_{j,l}|}_{*}$$



$$\lambda_j = \sum_{l \in S, l \neq j} |\langle A_l, A_j \rangle| \leq \mu_{\perp}(k-1)$$

$$\forall j \in S$$

By Gershgorin's disk theorem

$$\lambda_j \in [1 - \mu_{\perp}(k-1), 1 + \mu_{\perp}(k-1)]$$

Propositions: $\mu_1(k) + \mu_1(k-1) < 1$

Theorem A is normalized

If $\mu_1(k) + \mu_1(k-1) < 1$

then ERC_k holds

Coherence
Condition

CC_k

Rk: $\mu_1(2k-1) \leq \mu_1(k) + \mu_1(k-1)$

$CC_k \Rightarrow \mu_1(2k-1) < 1 \Rightarrow RIP_{2k}$

$CC_k \Rightarrow ERC_k$

Proof: $CC_k \Rightarrow ERC_k$

We need to prove that:

A_S injective $\left. \begin{array}{l} \text{implied by} \\ \mu_1(2k-1) < 1 \Rightarrow RIP_{2k} \end{array} \right\}$

$$\cdot \|A_S^T r\|_\infty > \|A_{S^c}^T r\|_\infty$$

where $r = A_S z$ with $z \neq 0$

• Get $z \neq 0$, set $r = A_S z$, and choose:

$$l \in S \text{ s.t. } |z_l| = \|z\|_\infty$$

• Note that for $j \in S^c$

$$\begin{aligned} |\langle A_j, r \rangle| &= \left| \sum_{i \in S} z_i \langle A_i, A_j \rangle \right| \\ &\leq \sum_{i \in S} |z_i| |\langle A_i, A_j \rangle| \\ &\leq |z_l| \mu_1(k) \\ &\stackrel{\text{---}}{\equiv} \end{aligned}$$

• And for $i \in S$,

$$|\langle A_l, r \rangle| = \left| \sum_{j \in S} z_j \langle A_l, A_j \rangle \right|$$

$$\geq |z_l| |\langle A_l, A_e \rangle| - \sum_{\substack{j \neq l \\ j \in S}} |z_j| |\langle A_j, A_e \rangle|$$

$$\geq |z_l| - |z_l| \mu_1(k-1)$$

$$= |z_l| \underbrace{(1 - \mu_1(k-1))}_{> \mu_1(k)}$$

$$\|A_{S^c}^T\|_{\infty} \geq |\langle A_e, z \rangle| \geq |z_l| (1 - \mu_1(k-1))$$

$$> |z_l| \mu_1(k)$$

$$\geq \|A_{S^c}^T z\|_{\infty} \quad \square$$

$$CC_k \Rightarrow RIP_k$$

$$CC_k \Rightarrow ERC_k$$

II) Stability and robustness

Stability : z^* is not sparse

Robustness : c is not zero

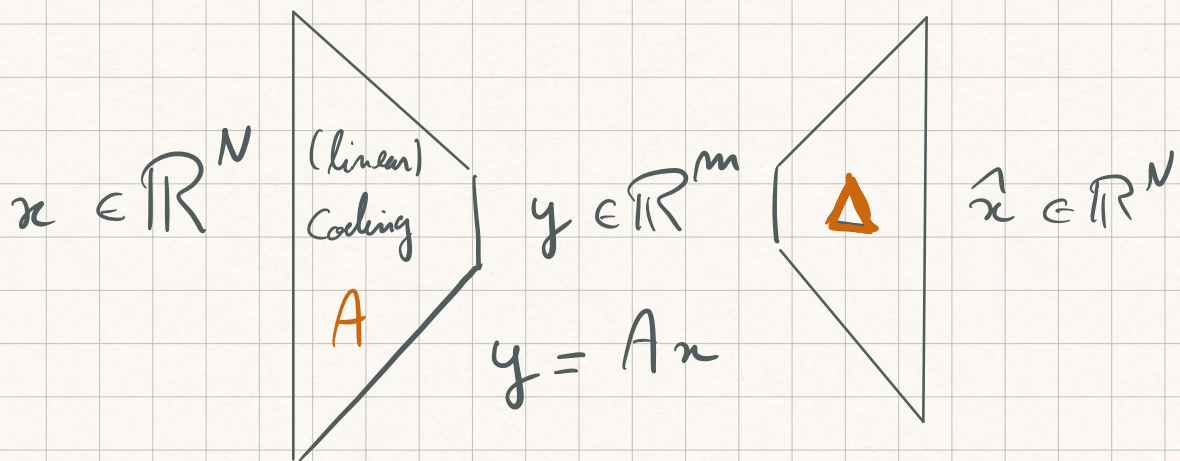
Instance Optimality

$$\sigma_k(x)_p := \inf \left\{ \|x - z\|_p : z \in \Sigma_k \right\}$$

- $k \in [N]$ sparsity
- $p \in [1, \infty]$ l_p -norm

Rk: $x \in \Sigma_k$, $\sigma_k(x)_p = 0$

Coding - Decoding Scheme



$\Delta: \mathbb{R}^m \rightarrow \mathbb{R}^N$ decoder

Def l_p -instance optimality of order k

We say that Δ is

l_p -instance optimal of order k

iff $\exists C > 0, \forall x \in \mathbb{R}^N,$

$$\|x - \Delta(Ax)\|_p \leq C \sigma_k(x)_p$$

Theorem Let $A \in \mathbb{R}^{m \times N}$ be given.

If $\exists \Delta$ s.t. (A, Δ) is l_1 -instance optimal
of order k with constant $C > 0$

then

|| 0 .

$\forall v \in \text{ker } A,$

$$\|v\|_1 \leq C \sigma_{2k}(v) \quad (**)$$

($C=2$ is the NSP_1)

Conversely if $(**)$ holds

then $\exists \Delta$ s.t. (A, Δ) is l_1 -instance optimal
of order k and constant $2C$.

Proof: Let $v \in \text{ker } A$

Let S be an index of the k largest
entries of v

$$\text{Inst. Opt} \Rightarrow -v_S = \Delta(\underbrace{A(-v_S)}_{Av_{S^c}}) = \Delta(Av_{S^c})$$

$$\|v\|_1 = \|v_S + v_{S^c}\|_1 = \|v_{S^c} - \Delta(Av_{S^c})\|_1$$

$$\leq C \underbrace{\sigma_k(v_{S^c})_1}_{\text{sum on the } N-2k \text{ least abs. val coeff}} = C \sigma_{2k}(v)_1$$

Conversely, Assume $(**)$ condition.

Define Δ as:

$$\Delta(y) = \arg \min_{\substack{z: \\ Az=y}} \left\{ \sigma_k(z)_1 \right\} \quad \leftarrow y = Ax \text{ is feasible}$$

Let $x \in \mathbb{R}^N$, $(**)$ with $v = x - \Delta(Ax) \in \text{ker } A$

$$(Av = Ax - A(\underbrace{\Delta(Ax)}_{z^*}) = 0)$$

Ax

$$\|x - \Delta(Ax)\|_2 \leq C \sigma_{2k}(x - \Delta(Ax))_1$$

$$\leq C \left[\sigma_k(x)_1 + \sigma_k(\Delta(Ax))_1 \right] \\ \leq \sigma_k(x)_1 \quad (x \text{ feasible})$$

$$\leq 2C \sigma_k(x)_1 \quad \square$$

Theorem If (A, Δ) are l_1 -instance optimal of order k and constant $C > 0$

then

$$m \geq c k \ln \left(\frac{eN}{k} \right)$$

where c depends only on C .

Def Stable NSP with constant

$$0 < \rho < 1$$

iff $\forall v \in \ker A, \forall S \subset [N] \text{ i.t. } \#S = k,$
 $\|v_S\|_1 \leq \rho \|v_S\|_1$

Theorem Assume A satisfies Stable NSP of

order k and constant $0 < \rho < 1$

Then $\forall x \in \mathbb{R}^N$, any solution \hat{u} of

Best Pursuit:

$$\hat{u} \in \arg \min_{Az = Ax} \|z\|_1$$

is such that

$$\|x - \hat{u}\|_1 \leq \frac{2(1+\rho)}{1-\rho} \sigma_k(x)_1$$